

Theory I Algorithm Design and Analysis

(5 Hashing)

Prof. Th. Ottmann

The dictionary problem



Different approaches to the dictionary problem:

- Previously: Structuring the set of actually occurring keys: lists, trees, graphs, ...
- Structuring the complete universe of all possible keys: hashing

Hashing describes a special way of storing the elements of a set by breaking down the universe of possible keys.

The position of the data element in the memory is given by computation directly from the key.

Hashing



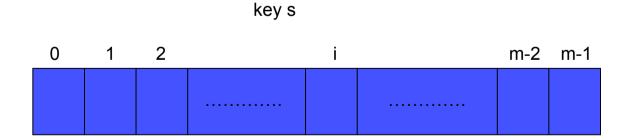
Dictionary problem:

Lookup, insertion, deletion of data sets (keys)

Place of data set *d*: computed from the key *s* of *d*

- \rightarrow no comparisons
- \rightarrow constant time

Data structure: linear field (array) of size *m* Hash table



The memory is divided in *m* containers (buckets) of the same size.

Hash tables - examples



Examples:

•

- Compilers i int 0x87C50FA4 j int 0x87C50FA8 x double 0x87C50FAC name String 0x87C50FB2
 - •••
- Environment variables (key, attribute) list EDITOR=emacs GROUP=mitarbeiter HOST=vulcano HOSTTYPE=sun4 LPDEST=hp5 MACHTYPE=sparc
 - • •
- Executable programs
 - PATH=~/bin:/usr/local/gnu/bin:/usr/local/bin:/usr/bin:/bin:

Implementation in Java



```
class TableEntry {
   private Object key, value;
abstract class HashTable {
    private TableEntry[] tableEntry;
   private int capacity;
    // Construktor
   HashTable (int capacity) {
        this.capacity = capacity;
        tableEntry = new TableEntry [capacity];
        for (int i = 0; i \leq capacity-1; i++)
            tableEntry[i] = null;
    // the hash function
   protected abstract int h (Object key);
   // insert element with given key and value (if not there already)
    public abstract void insert (Object key Object value);
    // delete element with given key (if there)
   public abstract void delete (Object key);
    // locate element with given key
    public abstract Object search (Object key);
} // class hashTable
```

Hashing - problems



1. Size of the hash table

Only a small subset *S* of all possible keys (the universe) *U* actually occurs

- 2. Calculation of the address of a data set
 - keys are not necessarily integers
 - index depends on the size of hash table

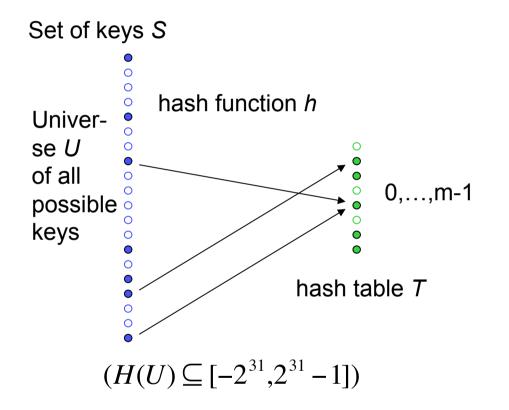
In Java:

```
public class Object {
    ...
    public int hashCode() {...}
    ...
}
```

The universe U should be distributed as evenly as possibly to the numbers -2^{31} , ..., $2^{31}-1$.

Hash function (1)





h(*s*) = hash address

 $h(s) = h(s') \iff s \text{ and } s' \text{ are synonyms with respect to } h$ address collision

Hash function (2)

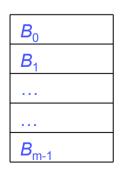


Definition: Let *U* be a universe of possible keys and $\{B_0, \ldots, B_{m-1}\}$ a set of *m* buckets for storing elements from *U*. Then a hash function is a total mapping

$$h: U \rightarrow \{0, \dots, m-1\}$$

mapping each key $s \in U$ to a number h(s)(and the respective element to the bucket $B_{h(s)}$).

• The bucket numbers are also called hash addresses, the complete set of buckets is called hash table.



Address collisions



- A hash function *h* calculates for each key *s* the number of the associated bucket.
- It would be ideal if the mapping of a data set with key s to a bucket h(s) was unique (one-to-one): insertion and lookup could be carried out in constant time (O(1)).
- In reality, there will be collisions: several elements can be mapped to the same hash address. Collisions have to be treated (in one way or another).



Example for U: all names in Java with length $\leq 40 \rightarrow |U| = 62^{40}$

If |U| > m: address collisions are inevitable

Hashing methods:

- 1. Choice of a hash function that is as "good" as possible
- 2. Strategy for resolving address collisions

Load factor α :

$$\alpha = \frac{\# \text{ stored keys}}{\text{size of the hash table}} = \frac{|S|}{m} = \frac{n}{m}$$

Assumption: table size *m* is fixed

Requirements for good hash functions



Requirements

- A collision occurs if the bucket $B_{h(s)}$ for a newly inserted element with key *s* is already taken.
- A hash function *h* is called perfect for a set S of keys if no collisions will occur for S.
- If *h* is perfect and |S| = *n*, then *n* ≤ *m*.
 The load factor of the hash table is *n/m* ≤ 1.
- A hash function is well chosen if
 - the load factor is as high as possible,
 - for many sets of keys the # of collisions is as small as possible,
 - it can be computed efficiently.

Example of a hash function



Example: hash function for strings

```
public static int h (String s){
    int k = 0, m = 13;
    for (int i=0; i < s.length(); i++)
        k += (int)s.charAt (i);
    return ( k%m );
}</pre>
```

The following hash addresses are generated for m = 13.

| key s | h(s) | |
|-------|------|--|
| Test | 0 | |
| Hallo | 2 | |
| SE | 9 | |
| Algo | 10 | |

The greater the choice of *m*, the more perfect *h* becomes.

Probability of collision (1)



Choice of the hash function

- The requirements high load factor and small number of collisions are in conflict with each other. We need to find a suitable compromise.
- For the set S of keys with |S| = n and buckets $B_0, ..., B_{m-1}$:
 - for n > m conflicts are inevitable
 - for n < m there is a (residual) probability $P_{\kappa}(n,m)$ for the occurrence of at least one collision.

How can we find an estimate for $P_{\kappa}(n,m)$?

- For any key *s* the probability that h(s) = j with $j \in \{0, ..., m 1\}$ is: $P_{\kappa}[h(s) = j] = 1/m$, provided that there is an equal distribution.
- We have P_K(n,m) = 1 P_{¬K}(n,m), if P_{¬K}(n,m) is the probability that storing of n elements in m buckets leads to no collision.

Probability of collision (2)



On the probability of collisions

- If *n* keys are distributed sequentially to the buckets $B_0, ..., B_{m-1}$ (with equal distribution), each time we have P[h(s) = j] = 1/m.
- The probability P(i) for no collision in step *i* is P(i) = (m (i 1))/m
- Hence, we have

$$P_{K}(n,m) = 1 - P(1) * P(2) * \dots * P(n) = 1 - \frac{m(m-1)\dots(m-n+1)}{m^{n}}$$

For example, if m = 365, P(23) > 50% and $P(50) \approx 97\%$ ("birthday paradox")

Common hash functions



Hash fuctions used in practice:

- see: D.E. Knuth: *The Art of Computer Programming*
- For *U* = integer the [divisions-residue method] is used:

 $h(s) = (a \times s) \mod m \ (a \neq 0, a \neq m, m \text{ prime})$

• For strings of characters of the form $s = s_0 s_1 \dots s_{k-1}$ one can use:

$$h(s) = \left(\left(\sum_{i=0}^{k-1} B^i s_i \right) \mod 2^w \right) \mod m$$

e.g. B = 131 and w = word width (bits) of the computer (w = 32 or w = 64 is common).

Simple hash function



Choice of the hash function

- simple and quick computation
- even distribution of the data (example: compiler)

(Simple) division-residue method

 $h(k) = k \mod m$

How to choose m?

Examples:

a) $m \text{ even } \rightarrow h(k) \text{ even } \Leftrightarrow k \text{ even}$

Problematic if the last bit has a meaning (e.g. 0 = female, 1 = male)

b) $m = 2^p$ yields the p lowest dual digits of k

Rule: Choose *m* prime, and *m* is not a factor of any $r^i + j$,

where *i* and *j* are small, non-negative numbers and *r* is the radix of the representation.

Multiplicative method (1)

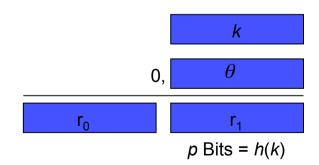


Choose constant θ , $0 < \theta < 1$

- 1. Compute $k\theta \mod 1 = k\theta \lfloor k\theta \rfloor$
- 2. $h(k) = \lfloor m(k\theta \mod 1) \rfloor$

Choice of *m* is uncritical, choose $m = 2^p$:

Computation of h(k):





Example:

$$\begin{aligned} \theta &= \frac{\sqrt{5} - 1}{2} \approx 0.6180339 \\ k &= 123456 \\ m &= 10000 \\ h(k) &= \left[10000(123456 * 0.61803...mod1) \right] \\ &= \left[10000(76300,0041151...mod1) \right] \\ &= \left[41.151... \right] = 41 \end{aligned}$$
Of all numbers $0 \le \theta \le 1$, $\frac{\sqrt{5} - 1}{2}$ leads to the most even distribution.

Universal hashing



Problem: if *h* is fixed \rightarrow there are $S \subseteq U$ with many collisions

Idea of universal hashing:

Choose hash function *h* randomly

H finite set of hash functions

$$h \in H : U \rightarrow \{0, \dots, m-1\}$$

Definition: *H* is universal, if for arbitrary $x, y \in U$:

$$\frac{\left|\{h \in H \mid h(x) = h(y)\}\right|}{\left|H\right|} \le \frac{1}{m}$$

Hence: if x, $y \in U$, H universal, $h \in H$ picked randomly

$$\Pr_H(h(x) = h(y)) \le \frac{1}{m}$$



Definition:

$$\delta(x, y, h) = \begin{cases} 1, \text{ if } h(x) = h(y) \text{ and } x \neq y \\ 0, \text{ otherwise} \end{cases}$$

Extension to sets:

$$\delta(x,S,h) = \sum_{s \in S} \delta(x,s,h)$$
$$\delta(x,y,G) = \sum_{h \in G} \delta(x,y,h)$$

Corollary: *H* is universal, if for any $x, y \in U$

$$\delta(x, y, H) \leq \frac{|H|}{m}$$

A universal class of hash functions



Assumptions:

- $|U| = p (p \text{ prime}) \text{ and } U = \{0, ..., p-1\}$
- Let $a \in \{1, ..., p-1\}$, $b \in \{0, ..., p-1\}$ and $\underline{h}_{\underline{a},\underline{b}} : \underline{U} \rightarrow \{0,...,m-1\}$ be defined as follows

 $h_{a,b} = ((ax+b) \mod p) \mod m$

Then:

The set

$$H = \{h_{a,b} \mid 1 \le a \le p-1, \ 0 \le b \le p-1\}$$

is a universal class of hash functions.



Hash table *T* of size 3, |U| = 5

Consider the 20 functions (set *H*):

| x+0 2 | x+0 | 3 <i>x</i> +0 | 4 <i>x</i> +0 |
|-------------|---------------|---------------|---------------|
| <i>x</i> +1 | 2x+1 | 3 <i>x</i> +1 | 4 <i>x</i> +1 |
| <i>x</i> +2 | 2 <i>x</i> +2 | 3 <i>x</i> +2 | 4 <i>x</i> +2 |
| <i>x</i> +3 | 2 <i>x</i> +3 | 3 <i>x</i> +3 | 4 <i>x</i> +3 |
| <i>x</i> +4 | 2 <i>x</i> +4 | 3 <i>x</i> +4 | 4 <i>x</i> +4 |

each (mod 5) (mod 3)

and the keys 1 und 4

We get:

```
(1*1+0) \mod 5 \mod 3 = 1 = (1*4+0) \mod 5 \mod 3
(1*1+4) \mod 5 \mod 3 = 0 = (1*4+4) \mod 5 \mod 3
(4*1+0) \mod 5 \mod 3 = 1 = (4*4+0) \mod 5 \mod 3
(4*1+4) \mod 5 \mod 3 = 0 = (4*4+4) \mod 5 \mod 3
```

Possible ways of treating collisions



Treatment of collisions:

- Collisions are treated differently in different methods.
- A data set with key *s* is called a colliding element if bucket $B_{h(s)}$ is already taken by another data set.
- What can we do with colliding elements?

1. Chaining: Implement the buckets as linked lists. Colliding elements are stored in these lists.

2. Open Addressing: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called probing.