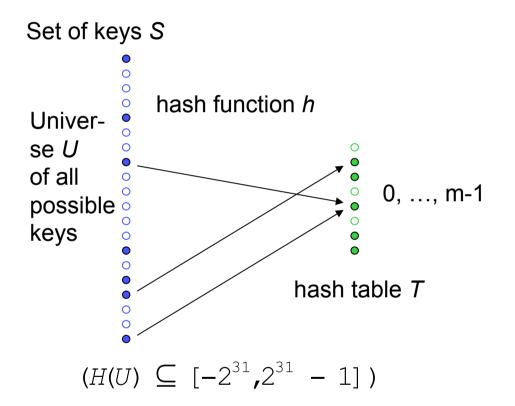


# Theory I Algorithm Design and Analysis

(7 Hashing: Open Addressing)

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## Hashing: General Framework



*h*(*s*) = hash address

 $h(s) = h(s') \iff s$  and s' are synonyms with respect to haddress collision

# Possible ways of treating collisions



#### Treatment of collisions:

- Collisions are treated differently in different methods.
- A data set with key *s* is called a colliding element if bucket  $B_{h(s)}$  is already taken by another data set.
- What can we do with colliding elements?

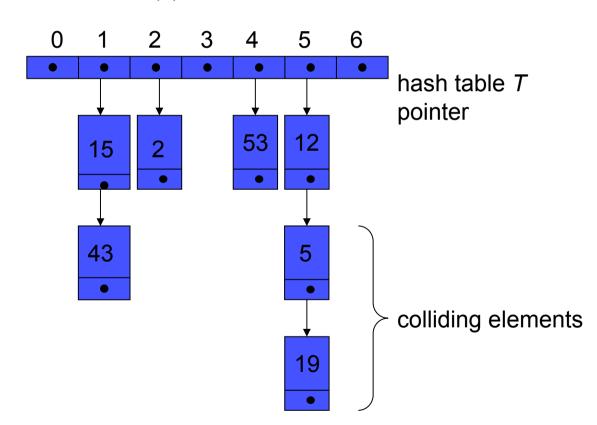
1. Chaining: Implement the buckets as linked lists. Colliding elements are stored in these lists.

2. Open Addressing: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called probing.

# Hashing by chaining



Keys are stored in overflow lists



 $h(k) = k \mod 7$ 

This type of chaining is also known as direct chaining.

# Open addressing



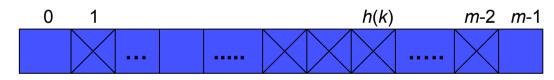
#### Idea:

Store colliding elements in vacant ("open") buckets of the hash table If T[h(k)] is taken, find a different bucket for *k* according to a fixed rule

#### **Example**:

Consider the bucket with the next smaller index:

 $(h(k) - 1) \mod m$ 



General:

Consider the sequence

(*h*(*k*) - *j*) mod *m* 

j = 0, ..., m-1

## Probe sequences



#### Even more general:

Consider the probe sequence

 $(h(k) - s(j,k)) \mod m$ 

j = 0, ..., m-1, for a given function s(j,k)

## **Examples** for the function

s(j,k) = j(linear probing) $s(j,k) = (-1)^j * \left[\frac{j}{2}\right]^2$ (quadratic probing)s(j,k) = j \* h'(k)(double hashing)

**Properties** of *s*(*j*,*k*)

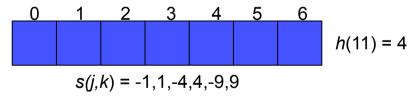
Sequence

 $(h(k) - s(0,k)) \mod m,$  $(h(k) - s(1,k)) \mod m,$ 

 $(h(k) - s(m-2,k)) \mod m,$  $(h(k) - s(m-1,k)) \mod m$ 

should result in a permutation of 0, ..., *m*-1.

**Example**: Quadratic probing



**Critical**:

Deletion of data sets  $\rightarrow$  mark as deleted

(Insert 4, 18, 25; delete 4; lookup 18, 25)



## Open addressing



```
class OpenHashTable extends HashTable {
    // in HashTable: TableEntry [] T;
   private int [] tag;
    static final int EMPTY = 0;
   static final int OCCUPIED = 1;
    static final int DELETED = 2;
   // Constructor
   OpenHashTable (int capacity) {
        super(capacity);
        tag = new int [capacity];
        for (int i = 0; i < capacity; i++) {
            tag[i] = EMPTY;
    // The hash function
   protected int h (Object key) {...}
    // Function s for probe sequence
   protected int s (int j, Object key) {
        // quadratic probing
        if (j % 2 == 0)
            return ((j + 1) / 2) * ((j + 1) / 2);
        else
            return -((j + 1) / 2) * ((j + 1) / 2);
```

## **Open addressing – lookup**



```
public int searchIndex (Object key) {
   /* searches for an entry with the given key in the hash table and
      returns the respective index or -1 */
   int i = h(key);
   while (tag[i] != EMPTY &&!key.equals(T[i].key)) {
       // Next entry in probing sequence
       i = (h(key) - s(j++, key))  capacity;
       if (i < 0)
           i = i + capacity;
   if (key.equals(T[i].key) && tag[i] == OCCUPIED)
       return i;
   else
       return -1;
public Object search (Object key) {
   /* searches for an entry with the given key in the hash table and
      returns the respective value or NULL */
   int i = searchIndex (key);
   if (i \ge 0)
       return T[i].value;
   else
       return null;
```

# Open addressing – insert



```
public void insert (Object key, Object value) {
    // inserts an entry with the given key and value
    int j = 1; // next index of probing sequence
    int i = h(key);
    while (tag[i] == OCCUPIED) {
        i = (h(key) - s(j++, key)) % capacity;
        if (i < 0)
            i = i + capacity;
    }
    T[i] = new TableEntry(key, value);
    tag[i] = OCCUPIED;
}</pre>
```

# Open addressing – delete



```
public void delete (Object key) {
    // deletes entry with given key from the hash table
    int i = searchIndex(key);
    if (i >= 0) {
        // Successful search
        tag[i] = DELETED;
    }
}
```

## Test program



```
public class OpenHashingTest {
    public static void main(String args[]) {
        Integer[] t= new Integer[args.length];
        for (int i = 0; i < args.length; i++)
            t[i] = Integer.valueOf(args[i]);
        OpenHashTable h = new OpenHashTable (7);
        for (int i = 0; i <= t.length - 1; i++) {
            h.insert(t[i], null);#
            h.printTable ();
        }
        h.delete(t[0]); h.delete(t[1]);
        h.delete(t[6]); h.printTable();
    }
}</pre>
```

#### Call:

java OpenHashingTest 12 53 5 15 2 19 43

#### **Output** (quadratic probing):

[]	[ ]	[ ]	[]	[]	(12)	[ ]
[]	[]	[ ]	[]	(53)	(12)	[ ]
[]	[]	[ ]	[]	(53)	(12)	(5)
[]	(15)	[ ]	[]	(53)	(12)	(5)
[]	(15)	(2)	[]	(53)	(12)	(5)
(19)	(15)	(2)	[]	(53)	(12)	(5)
(19)	(15)	(2)	(43)	(53)	(12)	(5)
(19)	(15)	(2)	{43}	{53}	{12}	(5)

## Probe sequences – linear probing



s(j,k) = j

Probe sequence for *k*:

*h*(*k*), *h*(*k*)-1, ..., 0, m-1, ..., *h*(*k*)+1,

Problem:

"primary clustering"

 0
 1
 2
 3
 4
 5
 6

 5
 53
 12
 12

*Pr* (next object ends at position 2) = 4/7

*Pr* (next object ends at position 1) = 1/7

Long chains are extended with higher probability than short ones.

# Efficiency of linear probing



Successful search:

$$C_n \approx \frac{1}{2} \left( 1 + \frac{1}{(1 - \alpha)} \right)$$

Failed search:

$$C'_{n} \approx \frac{1}{2} \left( 1 + \frac{1}{(1-\alpha)^{2}} \right)$$

α	C <sub>n</sub> (successful)	$C'_n$ (failed)
0.50	1.5	2.5
0.90	5.5	50.5
0.95	10.5	200.5
1.00	-	-

Efficiency of linear probing decreases drastically as soon as the load factor  $\alpha$  gets close to the value 1.



$$\mathbf{s}(\mathbf{j},\mathbf{k}) = (-1)^{j} * \left[\frac{j}{2}\right]^{2}$$

Probe sequence for *k*:

 $h(k), h(k)+1, h(k)-1, h(k)+4, \dots$ 

Permutation, if m = 4l + 3 is prime.

Problem: secondary clustering, i.e. two synonyms *k* and *k'* always run through the same probe sequence.

# Efficiency of quadratic probing



Successful search:

$$C_n \approx 1 - \frac{\alpha}{2} + \ln\left(\frac{1}{(1-\alpha)}\right)$$

Failed search:

$$C'_n \approx \frac{1}{1-\alpha} - \alpha + \ln\left(\frac{1}{(1-\alpha)}\right)$$

α	C <sub>n</sub> (successful)	C´_n(failed)
0.50	1.44	2.19
0.90	2.85	11.40
0.95	3.52	22.05
1.00	_	_

# **Double hashing**



Idea: Choose another hash function h'

 $s(j,k) = j \cdot h'(k)$ 

Probe sequence for *k*:

```
h(k), h(k)-h'(k), h(k)-2h'(k), ...
```

Requirement:

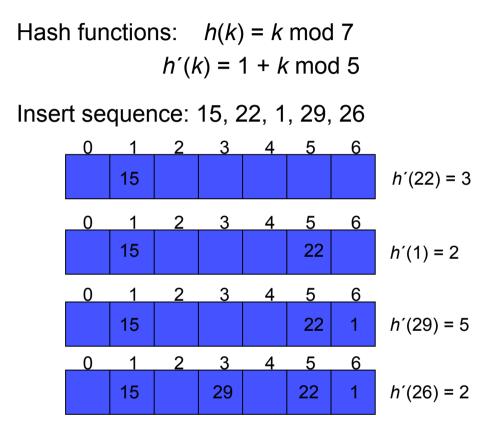
Probing sequence must correspond to a permutation of the hash addresses.

```
Hence:
h'(k) \neq 0 and h'(k) no factor of m, i.e. h'(k) does not divide m.
Example:
```

 $h'(k) = 1 + (k \mod (m-2))$ 

# Example





In this example we can do with a single probing step almost every time.

- Double hashing is as efficient as uniform probing.
- Double hashing is simpler to implement.

# Improving successful search – motivation



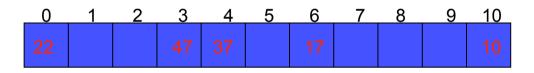
Hash table of size 11; double hashing with

 $h(k) = k \mod 11$  and

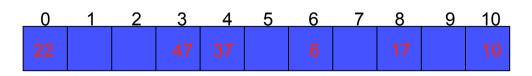
 $h'(k) = 1 + (k \mod (11 - 2)) = 1 + (k \mod 9)$ 

Already inserted: 22, 10, 37, 47, 17 Yet to be inserted: 6 and 30

$$h(6) = 6, h'(6) = 1 + 6 = 7$$



h(30) = 8, h'(30) = 1 + 3 = 4





In general:

Insert:

- k collides with  $k_{old}$  in T[i], i.e.  $i = h(k) s(j,k) = h(k_{old}) s(j',k_{old})$
- $k_{old}$  is already stored in T[i]

Idea:

Find a vacant bucket for k or kold

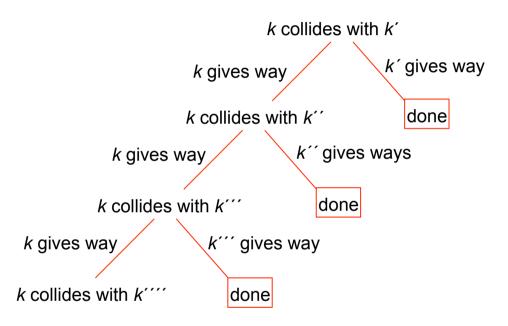
Two options:

- (O1)  $k_{old}$  remains in T[i]consider new position h(k) - s(j+1,k) for k
- (O2) k replaces  $k_{old}$ consider new position  $h(k_{old}) - s(j'+1, k_{old})$  for  $k_{old}$
- if (O1) or (O2) finds a vacant bucket then insert the respective key done else follow (O1) or (O2) further

# Improving successful search



Brent's method: only follow (O1)



Binary tree probing: follow (O1) and (O2)

## Improving successful search

Problem:  $k_{old}$  replaced by k

 $\rightarrow$  next position in probe sequence for  $k_{old}$ ?

Giving way is simple for  $k_{old}$  if:

 $s(j, k_{old}) - s(j - 1, k_{old}) = s(1, k_{old})$ 

for all  $1 \le j \le m - 1$ .

This is, e.g., true for linear probing and double hashing.

$$C_n^{Brent} \approx 1 + \frac{\alpha}{2} + \frac{\alpha^3}{4} + \frac{\alpha^4}{15} + \dots < 2.5$$
$$C_n^{'} \approx \frac{1}{1 - \alpha}$$

$$C_n^{Binary tree} \approx 1 + \frac{\alpha}{2} + \frac{\alpha^3}{4} + \frac{\alpha^4}{15} + \dots < 2.2$$



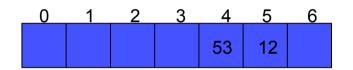


# Example



Hash functions:  $h(k) = k \mod 7$  $h'(k) = 1 + k \mod 5$ 

Insert sequence: 12, 53, 5, 15, 2, 19



*h*(5) = 5 occupied by *k*' = 12

Consider:

 $h'(5) = 1 \rightarrow h(5) - 1 \cdot h'(5)$ 

 $\rightarrow$  5 pushes 12 from its bucket

# Improving unsuccessful search

#### Lookup *k*:

k' > k in probe sequence  $\rightarrow$  lookup failed

### Insert:

smaller keys push away greater keys

## Invariant:

All keys in the probe sequence before *k* are smaller than *k* (but not necessarily in ascending order)

## Problems:

- The "pushing" process may trigger a "chain reaction"
- *k*' pushed away by *k*: position of *k*' in probe sequence?
- $\rightarrow$  Required:

 $s(j,k) - s(j-1,k) = s(1,k), 1 \le j \le m$ 

# Ordered hashing



Lookup

```
Input: key k

Output: Information about data set with key k, or null

Begin at i \in h(k)

while T[i] not empty and T[i] k < k do

i \in (i - s(1,k)) \mod m

end while;

if T[i] occupied and T[i] k = k

then search successful

else search failed
```

# Ordered hashing



Insert

Input: key k Begin at  $i \leftarrow h(k)$ while T[i] not empty and  $T[i] . k \neq k$  do if k < T[i].kthen if T[i] is removed then exit while-loop else // k pushes away T[i].kswap T[i].k with k  $i = (i - s(1,k)) \mod m$ end while; if T[i] is not occupied

then insert k in T[i]