

# Universal hashing

**Problem:** if  $h$  is fixed  $\rightarrow$  there are  $S \subseteq U$  with many collisions

**Idea of universal hashing:**

Choose hash function  $h$  **randomly**

$H$  finite set of hash functions

$$h \in H : U \rightarrow \{0, \dots, m-1\}$$

**Definition:**  $H$  is **universal**, if for arbitrary  $x, y \in U$ :

$$\frac{|\{h \in H \mid h(x) = h(y)\}|}{|H|} \leq \frac{1}{m}$$

Hence: if  $x, y \in U$ ,  $H$  universal,  $h \in H$  picked randomly

$$\Pr_H(h(x) = h(y)) \leq \frac{1}{m}$$

# A universal class of hash functions

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## Assumptions:

- $|U| < p$  ( $p$  prime) and  $U = \{0, \dots, p-1\}$
- Let  $a \in \{1, \dots, p-1\}$ ,  $b \in \{0, \dots, p-1\}$  and  $h_{a,b} : U \rightarrow \{0, \dots, m-1\}$  be defined as follows

$$h_{a,b} = ((ax+b) \bmod p) \bmod m$$

## Then:

The set

$$H = \{h_{a,b} \mid 1 \leq a \leq p-1, 0 \leq b \leq p-1\}$$

is a **universal class of hash functions**.

# Universal hashing - example

Hash table  $T$  of size 3,  $|U| = 5$

Consider the 20 functions (set  $H$ ):

$x+0$	$2x+0$	$3x+0$	$4x+0$
$x+1$	$2x+1$	$3x+1$	$4x+1$
$x+2$	$2x+2$	$3x+2$	$4x+2$
$x+3$	$2x+3$	$3x+3$	$4x+3$
$x+4$	$2x+4$	$3x+4$	$4x+4$

each  $(\text{mod } 5)$   $(\text{mod } 3)$  and the key

s  $1$  und  $4$ , let us consider the number of hash functions in  $H$ , such that  $h(1) = h(4)$ .

1 2 3 4

1 2 3 4

4 8 12 16

4 3 2 1

2 3 4 5

2 3 4 0

5 9 13 17

0 4 3 2

3 4 5 6

3 4 0 1

6 10 14 18

1 0 4 3

4 5 6 7

4 0 1 2

7 11 15 19

2 1 0 4

5 6 7 8

0 1 2 3

8 12 16 20

3 2 1 0

$a(1) + b$

$h'(1) = (a(1) + b) \text{ mod } 5$

$a(4) + b$

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each (mod 5) (mod 3) and the keys

1 und 4, let us consider the number of hash functions  $h$  in  $H$ , such that  $h(1) = h(4)$ .

1 2 3 4  
2 3 4 5  
3 4 5 6  
4 5 6 7  
5 6 7 8

① 2 3 ④  
2 3 4 0  
3 4 0 1  
4 0 1 2  
① 1 2 ③

4 8 12 16  
5 9 13 17  
6 10 14 18  
7 11 15 19  
8 12 16 20

④ 3 2 ①  
0 4 3 2  
1 0 4 3  
2 1 0 4  
③ 2 1 ①

$a(1) + b$

$h'(1) = (a(1) + b) \bmod 5$

$a(4) + b$

$h'(4) = (a(4) + b) \bmod 5$

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The set

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is a **universal class of hash functions**.

$$h_{a,b} = ((ax+b) \bmod p) \bmod m$$

$H = \{h_{a,b} \mid 1 \leq a \leq p-1, 0 \leq b \leq p-1\}$  is a universal class of hash functions.

### **Proof**

Consider two distinct keys  $x$  and  $y$  from  $\{0, \dots, p-1\}$ , so that  $x \neq y$ . For a given hash function  $h_{a,b}$ , we let

$$s = (ax + b) \bmod p,$$

$$t = (ay + b) \bmod p.$$

Firstly,  $s \neq t$  holds, since  $s - t \equiv a(x - y) \pmod{p}$ .

# Possible ways of treating collisions

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## Treatment of collisions:

- Collisions are treated differently in different methods.
- A data set with key  $s$  is called a **colliding element** if bucket  $B_{h(s)}$  is already taken by another data set.
- What can we do with colliding elements?
  1. **Chaining**: Implement the buckets as linked lists. Colliding elements are stored in these lists.
  2. **Open Addressing**: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called **probing**.

# Theory I

## Algorithm Design and Analysis

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(6 Hashing: Chaining)

*Prof. Th. Ottmann*



# Chaining (1)

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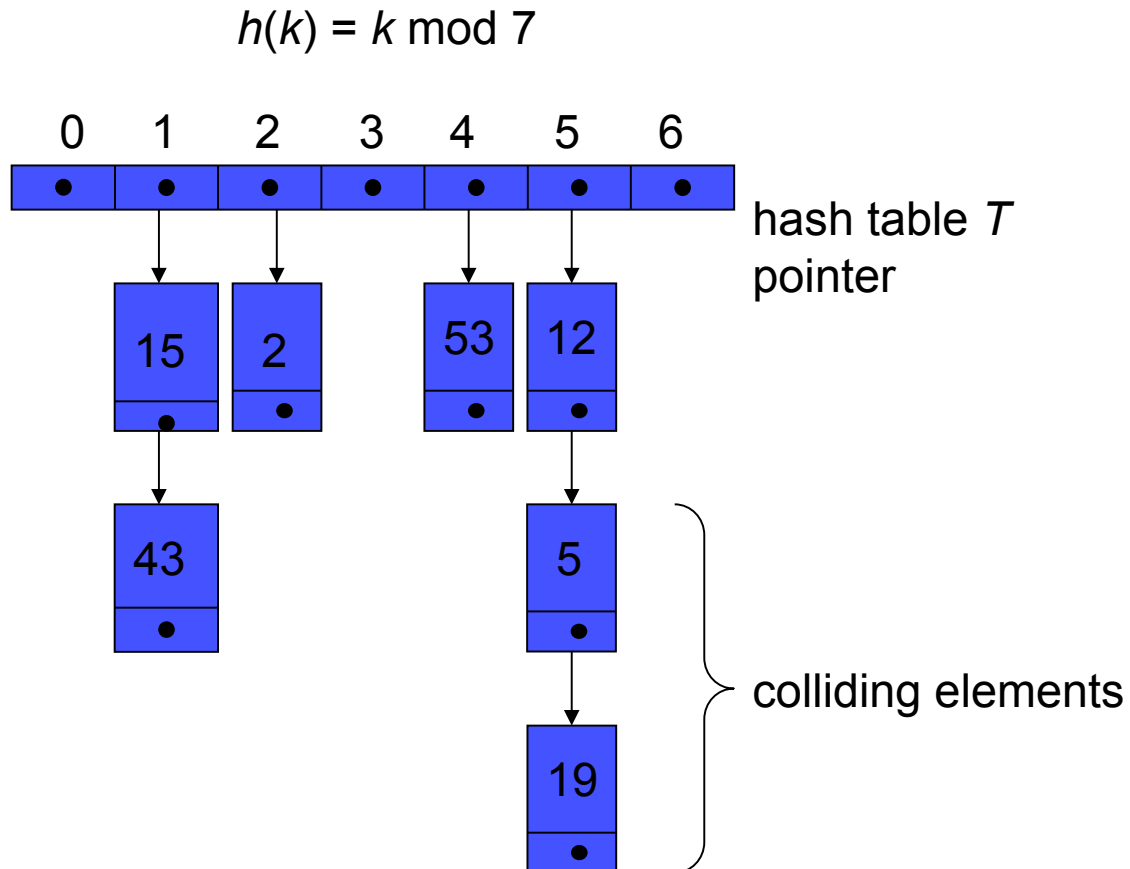
- The hash table is an array (length  $m$ ) of lists.  
Each bucket is realized by a list.

```
class hashTable {
    List[] ht;           // an array of lists
    hashTable (int m){  // Konstruktor
        ht = new List[m];
        for (int i = 0; i < m; i++)
            ht[i] = new List(); // Construct a list
    }
    ...
}
```

- Two different ways of using lists:
  1. **Direct chaining:**  
Hash table only contains list headers; the data sets are stored in the lists.
  2. **Separate chaining:**  
Hash table contains at most one data set in each bucket as well as a list header.  
Colliding elements are stored in the list.

# Hashing by chaining

Keys are stored in **overflow lists**



This type of chaining is also known as **direct chaining**.

# Chaining

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## Lookup key $k$

- Compute  $h(k)$  and overflow list  $T[h(k)]$
- Look for  $k$  in the overflow list

## Insert a key $k$

- Lookup  $k$  (fails)
- Insert  $k$  in the overflow list

## Delete a key $k$

- Lookup  $k$  (successfully)
- Remove  $k$  from the overflow list

→ only list operations

# Analysis of direct chaining

Uniform hashing assumption:

- All hash addresses are chosen with the same probability, i.e.:

$$Pr(h(k_j) = j) = 1/m$$

- independent from operation to operation

Average chain length for  $n$  entries:

$$n/m = \alpha$$

Definition:

$C'_n$  = Expected number of entries inspected during a failed search

$C_n$  = Expected number of entries inspected during a successful search

Analysis:

$$C'_n = \alpha$$

$$C_n \approx 1 + \frac{\alpha}{2}$$

# Chaining

## Advantages:

- +  $C_n$  and  $C'_n$  are small
- +  $\alpha > 1$  possible
- + real distances
- + suitable for secondary memory

## Efficiency of lookup

$\alpha$	$C_n$ (successful)	$C'_n$ (fail)
0.50	1.250	0.50
0.90	1.450	0.90
0.95	1.457	0.95
1.00	1.500	1.00
2.00	2.000	2.00
3.00	2.500	3.00

## Disadvantages:

- Additional space for pointers
- Colliding elements are outside the hash table

# Summary

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## Analysis of hashing with chaining:

- **worst case:**

$h(s)$  always yields the same value, all data sets are in a list.  
Behavior as in linear lists.

- **average case:**

- Successful lookup & delete: complexity (in inspections)  $\approx 1 + 0.5 \times \text{load factor}$
- Failed lookup & insert: complexity  $\approx \text{load factor}$

This holds for direct chaining, with separate chaining the complexity is a bit higher.

- **best case:**

lookup is an immediate success: complexity  $\in O(1)$ .